PCE Platform



PCE DESCRIPTION

CONAE Contact: Carlos Alonso

Tel: +54-2944-437901 / 426360 ext 104

Fax: +54-2944-437901 / 426360 ext. 108

e-mail: calonso@conae.gov.ar

Address: V. A. O'Connor 587 (8400), Bariloche, Argentina



The PCE (CONAE Standard Platform) is based on the SAC-C platform.

SAC-C was launched in November 2000.

It is operating from November 2000 flawlessly.



Two versions of PCE are presented.

PCE-1 is lighter and can be adapted to different node crossing time.

PCE-2 has more capabilities in terms of attitude control performance and can accommodate payloads heavier and more demanding in power.

PCE-2 is tailored for SSO with 6:00am/pm node crossing time.



PCE-1 Platform Characteristics

Life time

>4 years

Orbit

Height: 650 to 800 Km.

Type: Circular Sun-Synchronous, 9:30 am to 2:30 pm



PCE-1 Platform Characteristics

Radiation Tolerant

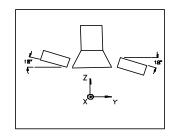
20 kRad

Redundancy

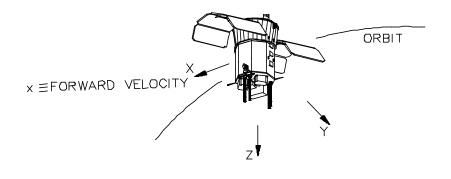
All subsystems fully redundant



PCE-1 Platform Characteristics



SOLAR PANELS DEPLOYMENT ANGLE DETAIL



EARTH

SAC-C Project



PCE-1 Platform Characteristics

Spacecraft Telemetry

S Band

Science

#S Band: 5Mbps

X Band: 320Mbps

On Board Data Storage

- #96Mbytes (bus housekeeping and instruments with low data storage requirements)
- #Data storage for instruments with higher requirements could be provided (up to 128Gbits)



PCE-1 Platform Characteristics

Spacecraft Attitude Control (on board)

Accuracy (mission mode)
0,2 deg

Knowledge (mission mode)

10 acrsec (satellite axis)

Stability 0,004 deg/sec (3 sigma)

Navigation (on board)

C/A Code GPS 30 meters (1 sigma)



PCE-1 Platform Characteristics

Spacecraft Attitude Control

Sensors:

horizon sensors, tri-axial magnetometers, star trackers, GPS, coarse sun sensors.

Actuators:

2 momentum wheels, 3 torque rods, 8 thrusters.



PCE-1 Platform Characteristics

Spacecraft Power

Bus Voltage 21 - 35 Volts

Solar Array Generated Power 560 to 600 Watts EOL (AsGs)

2 Nickel Hydrogen Batteries 12 Ah (25% max DoD)

Bus Power Consumption 130 Watts (average)

Max Payload Power 140 Watts (average)

SAC-C Project



PCE-1 Platform Characteristics

Mass Budget

Bus mass: 360 - 380 kg. Payload mass: Up to 200kg.



Spacecraft Propulsion System



12 kg of hydrazine 8 thrusters in dual configuration

Attitude Control during maneuvers is performed by off modulation.



PCE-2 Platform Characteristics

Life time

>5 years

Orbit

Height: 650 to 800 Km.

Type: Circular Sun-Synchronous, 06:00am/pm



PCE-2 Platform Characteristics

Radiation Tolerant
20 kRad

Redundancy
All subsystems fully redundant



PCE-2 Platform Characteristics

Spacecraft Telemetry

S Band

Science

- **#S Band: 5Mbps**
- **X Band: 320Mbps**

On Board Data Storage

- #96Mbytes (bus housekeeping and instruments with low data storage requirements)
- #Data storage for instruments with higher requirements could be provided (up to 128Gbits)



PCE-2 Platform Characteristics

Spacecraft Attitude Control (on board)

Accuracy (mission mode) 0,04deg

Knowledge (mission mode)
7 acrsec (satellite axis)

Stability
0,0005 deg/sec (3 sigma)

Navigation (on board)

C/A Code GPS 30 meters (1 sigma)



PCE-2 Platform Characteristics

Spacecraft Attitude Control

Sensors:

tri-axial magnetometers, star trackers, GPS, coarse sun sensors.

Actuators:

4 reaction wheels, 3 torque rods, 16 thrusters.

An Inertial Reference Unit can be also considered in the Attitude Control Subsystem baseline configuration if necessary. The performances included in this presentation does not take into account an IRU in the simulations.



PCE-2 Platform Characteristics

Spacecraft Power

Bus Voltage 64 - 78 Volts

Solar Array Generated Power 1700 Watts EOL (AsGs)

1 Nickel Hydrogen Batteries 132 Ah (20% max DoD)

Bus Power Consumption 300 Watts (average)

Max Payload Power

1000 / 3500 Watts (average/peak)

SAC-C Project



PCE-2 Platform Characteristics

Mass Budget

Bus mass: 680 to 790 kg. Payload mass: Up to 600kg.



PCE-2 Platform Characteristics

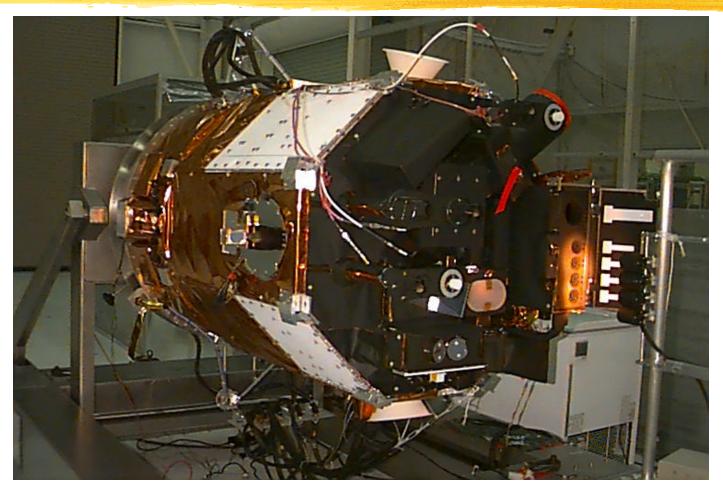
Spacecraft Propulsion System

Up to 80 kg of hydrazine 16 thrusters in dual configuration providing torque in all three axis.

Attitude Control during maneuvers is performed by off modulation.



SAC-C at Vandenberg





The End

